

Human Agent Joint Learning For Efficient Robot Manipulation Skill Acquisition

Topic Selection to Article Writeup | Ultimate Research Bootcamp
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Bootcamp 2026 417fc7e67e The orchestration loop — session \u0026
message array 417fc7e67e Which rung do you start on? 417fc7e67e
Multi-Modal Structure 417fc7e67e Failure to Reach the Groove
417fc7e67e Skill Learning Experiment 417fc7e67e Robust
Manipulation 417fc7e67e Seven skills, one ladder 417fc7e67e
Reinforcement Learning behind Humanoid Robot Explained -
Reinforcement Learning behind Humanoid Robot Explained 9
minutes, 51 seconds - In this video we will be training humanoid with
deep **learning**, first we are going to get an overview of how
humanoid works then ... 417fc7e67e Learning High-Level Policies
417fc7e67e Meta Features 417fc7e67e Model Parameterization
417fc7e67e Learning Reusable Manipulation Skills 417fc7e67e []
[] Human-Agent Joint Learning for Efficient Robot Manipulation Skill
Acquisition - [] [] Human-Agent Joint Learning for Efficient Robot
Manipulation Skill Acquisition 11 minutes, 48 seconds - Human,-
**Agent Joint Learning for Efficient Robot Manipulation Skill
Acquisition**, ICRA 2025, [] [] [] [] [] [] - iRASC ... 417fc7e67e
Playback 417fc7e67e Sequencing Motor Primitives 417fc7e67e
Spherical Videos 417fc7e67e Skill Generalization Summary
417fc7e67e Why combine robotics + an AI Harness 417fc7e67e
Adapting Skills to Geometric Object Features • Want to adapt skills
to geometric features of objects 417fc7e67e Skill Replay 417fc7e67e
How to Learn AI Agents before 2027 (Part 1) - How to Learn AI
Agents before 2027 (Part 1) 6 minutes, 45 seconds - Master the AI
learning, roadmap to move beyond basic prompting. Build the
agentic thinking **skills**, needed to operate a business ... 417fc7e67e
Learning to Monitor Skills 417fc7e67e Demo Bimanual Grasp
417fc7e67e Panel Discussion 417fc7e67e When reality differs —
grounded replanning 417fc7e67e Not one unicorn — a market
417fc7e67e Automating and Orchestrating AI 417fc7e67e Tilt Results
417fc7e67e Skill 2 — Prompt and context engineering 417fc7e67e
Skill 4 — Tools and function calling 417fc7e67e Keyboard shortcuts
417fc7e67e General 417fc7e67e Skill 1 — Python and the model APIs
417fc7e67e Learned Motor Primitives 417fc7e67e Weiming Zhi -
Imitation Learning of High Dimensional Robot Systems: From
Dexterous Manipulation to Mobile Manipulator Teams 417fc7e67e
Skill 6 — Evals and observability 417fc7e67e Reinforcement Learning
417fc7e67e Subtitles and closed captions 417fc7e67e Skill
Acquisition Summary 417fc7e67e The \$500K minimums, read out
417fc7e67e What AI Agent Skills Are and How They Work - What AI
Agent Skills Are and How They Work 12 minutes, 25 seconds - Ready
to become a certified watsonx Generative AI Engineer? Register now
and use code IBMTechYT20 for 20% off of your exam ... 417fc7e67e
Moving Beyond Simple AI Prompts 417fc7e67e Skill- α : Progressive
Agent Skill Generation via Reinforcement Learning - Skill- α :
Progressive Agent Skill Generation via Reinforcement Learning 7
minutes, 48 seconds - We propose a **Skill**,- α framework that

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automatically generates external **skills**, to increase the ability of large-scale language model ... 417fc7e67e Arming Your AI Workers With Tools 417fc7e67e Navigating the kitchen — sub-goals 417fc7e67e Hao-Shu Fang - Perioperation: Sensorizing Humans for Scalable Dexterous Manipulation Data 417fc7e67e Structuring Manipulation Tasks for More Efficient Learning (Oliver Kroemer, CMU) - Structuring Manipulation Tasks for More Efficient Learning (Oliver Kroemer, CMU) 1 hour, 2 minutes - Winter 2021 **Robotics**, Colloquium In the future, we want to create **robots**, with the robustness and versatility to operate in ... 417fc7e67e What the market pays, rung by rung 417fc7e67e A simple request — "\"get me a cup of oil\" 417fc7e67e A live Sentinel × ROS 2 demo 417fc7e67e Learning to Monitor Manipulation Skills 417fc7e67e Humanoid and dual-arm manipulation - Humanoid and dual-arm manipulation 2 minutes, 35 seconds - Imitation **learning**, and motion planning. 417fc7e67e The LLM: many transformer layers 417fc7e67e Predicting Feature Relevance 417fc7e67e Basic Grasp Example 417fc7e67e Skill 7 — Deployment and guardrails 417fc7e67e A list is not experience 417fc7e67e Agentic AI and Robotics - Step by Step Explanation - AI Harness, LLMs, ROS 2 - Agentic AI and Robotics - Step by Step Explanation - AI Harness, LLMs, ROS 2 7 minutes, 10 seconds - An AI **agent**, — a large language model wired to tools — can hold a conversation, call functions, and reason about a task. But how ... 417fc7e67e The stack: L1 harness · L2 ROS 2 graph · L3 verbs 417fc7e67e Perception — depth, detection \u0026amp; 6-DoF pose 417fc7e67e Jeannette Bohg - Demistifying VLA Performance in Contact-Rich Tasks and How to Fix Them 417fc7e67e Learning Versatile Manipulation Skills 417fc7e67e Defining Your AI Workforce 417fc7e67e Skill 5 — Multi-agent orchestration 417fc7e67e Transfer Learning Experiment 417fc7e67e Spotlight Session 417fc7e67e ICP — recovering the exact pose 417fc7e67e You already have some of these 417fc7e67e Search filters 417fc7e67e Scooping Granular Material 417fc7e67e Task decomposition (not the motion planner) 417fc7e67e Box Pushing Experiment 417fc7e67e RI Seminar: Tucker Hermans : Improving Multi-fingered Robot Manipulation... - RI Seminar: Tucker Hermans : Improving Multi-fingered Robot Manipulation... 54 minutes - RI Seminar: Tucker Hermans Improving Multi-fingered **Robot Manipulation**, by Unifying **Learning**, and Planning ... 417fc7e67e Inside the AI Harness — agent, messages, tools, memory 417fc7e67e Oliver Brock - Is the Bottleneck Really Shifting 417fc7e67e System Overview 417fc7e67e Navigation — Nav2 \u0026amp; the DWB local planner 417fc7e67e The arm — MoveIt \u0026amp; RRT-Connect 417fc7e67e AI Agent Engineer: 7 Skills That Pay \$500K - AI Agent Engineer: 7 Skills That Pay \$500K 5 minutes, 43 seconds - A \$500000 AI **agent**, engineer job has no degree behind it. That's the point. **Agent**, engineering is too new for universities to teach it ... 417fc7e67e Probabilistic Model Structure 417fc7e67e Manipulation Learning 417fc7e67e Feature Selection 417fc7e67e A job with no degree behind it 417fc7e67e Learning Motor Primitives for Mode Transitions 417fc7e67e Operating a Pepper Mill 417fc7e67e Pouring Granular Material 417fc7e67e The one skill that moves the number 417fc7e67e RI Seminar: Oliver Kroemer : Learning Robot Manipulation Skills... - RI Seminar: Oliver Kroemer : Learning Robot Manipulation Skills... 53 minutes - Learning Robot Manipulation Skills, through Experience and Generalization Oliver Kroemer Assistant Professor **Robotics**, Institute, ... 417fc7e67e RSS 2026 | 4th Workshop on Dexterous Manipulation: Scalable Learning for Human-Level Skills - RSS 2026 | 4th Workshop on Dexterous

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Manipulation: Scalable Learning for Human-Level Skills 2 hours, 49 minutes - 4th Workshop on Dexterous **Manipulation**,: Scalable **Learning**, for **Human**,-Level **Skills**, 00:00 Jeannette Bohg - Demistifying VLA ... 417fc7e67e Skill Demonstration 417fc7e67e How Robots Learned to Walk: From Hand-Engineered Control to Reinforcement Learning - How Robots Learned to Walk: From Hand-Engineered Control to Reinforcement Learning 42 minutes - Is legged locomotion actually a solved problem? In this episode of RobTalk, Felix Frank from our **Robot**, Intelligence team explains ... 417fc7e67e Human Agent Joint Learning for Efficient Robot Manipulation Skill Acquisition - Human Agent Joint Learning for Efficient Robot Manipulation Skill Acquisition 26 minutes - Presenter: Oh Seung-min - Department of Software Engineering 417fc7e67e Intro 417fc7e67e Shaking Granular Material 417fc7e67e Teaching robots to change their grip the way humans do - Teaching robots to change their grip the way humans do 1 minute, 22 seconds - It's easy for people to change they're holding an object, even if that means bracing it against the wall — but **robots**, find this ... 417fc7e67e The job posting that pays like that 417fc7e67e Motivation 417fc7e67e Skill 3 — Retrieval and vector databases 417fc7e67e

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